

## Ch. 9 - Center of Mass & Momentum

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### Main Point of Ch. 9 :

Momentum Conservation!  $\vec{p} = m\vec{v}$

For a system with translational invariance,

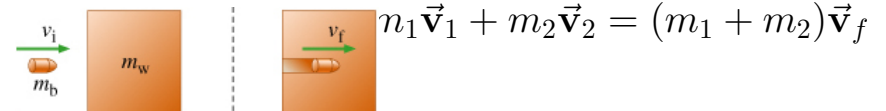
$$\vec{p}_i = \vec{p}_f$$

$$\star m_1\vec{v}_{1i} + m_2\vec{v}_{2i} = m_1\vec{v}_{1f} + m_2\vec{v}_{2f} \star$$

### Types of Collisions

1. inelastic collision most generic type; some energy lost  
perfectly inelastic collision collide and *stick*,

$$\therefore \vec{p}_{1i} + \vec{p}_{2i} = \vec{p}_f$$



2. elastic collision momentum *and* energy are conserved; e.g., medium energy billiards

$$\vec{p}_{1i} + \vec{p}_{2i} = \vec{p}_{1f} + \vec{p}_{2f}$$

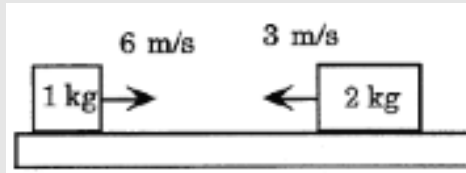
$$K_{1i} + K_{2i} = K_{1f} + K_{2f}$$



## Active Learning Exercise

### Problem: Perfectly Inelastic Collision

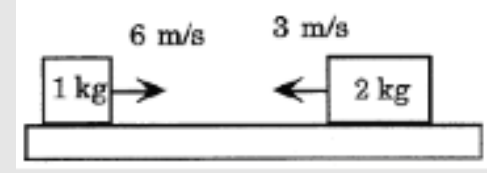
Two boxes are on a horizontal, frictionless surface. The boxes are sliding toward one another and subsequently collide. If the boxes stick together, **perfectly inelastically**, what velocity has the 1 kg box after the collision?



## Active Learning Exercise

### Problem: Elastic Collision

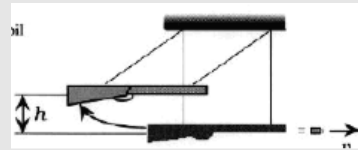
Two boxes are on a horizontal, frictionless surface. The boxes are sliding toward one another and collide. If the collision is **elastic**, meaning energy is conserved, what velocity has the 1 kg box after the collision? [use *solve*]



## Active Learning Exercise

### Problem: Example:

A 6.0 kg rifle is suspended by two long strings as shown. The rifle is fired and the recoil results in the rifle swinging backward to a maximum height  $h = 0.040$  m. What is the speed of the 0.010 kg bullet?



## 9.8 – 2D Collisions

### ► 2D Collisions

$$\vec{\mathbf{p}}_{1i} + \vec{\mathbf{p}}_{2i} = \vec{\mathbf{p}}_{1f} + \vec{\mathbf{p}}_{2f}$$
$$m_1 \vec{\mathbf{v}}_{1i} + m_2 \vec{\mathbf{v}}_{2i} = m_1 \vec{\mathbf{v}}_{1f} + m_2 \vec{\mathbf{v}}_{2f}$$

### ► Or in $x, y$ -component form:

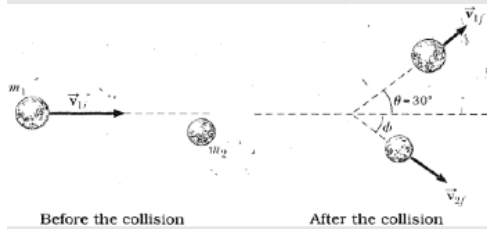
$$m_1 v_{1i} \cos \theta_{1i} + m_2 v_{2i} \cos \theta_{2i} = m_1 v_{1f} \cos \theta_{1f} + m_2 v_{2f} \cos \theta_{2f}$$

$$m_1 v_{1i} \sin \theta_{1i} + m_2 v_{2i} \sin \theta_{2i} = m_1 v_{1f} \sin \theta_{1f} + m_2 v_{2f} \sin \theta_{2f}$$

## Active Learning Exercise

### Problem: 2D Inelastic w/ angles

A bowling ball with mass  $m_1 = 2.0$  kg moving in the positive  $x$  direction with velocity  $3.0$  m/s strikes a pin with mass  $m_2 = 1.0$  kg. The pin is initially at rest. Immediately after the collision, the bowling ball has a velocity of  $1.5$  m/s at an angle of  $30^\circ$  with respect to the  $x$ -axis. What is the  $y$ -velocity of *the pin* after collision?



## 9.4 – Impulse

$$\begin{aligned}\vec{J} &= \int \text{Force} \cdot dt \\ &= \text{Force} \cdot \text{time}\end{aligned}$$

## 9.4 – Momentum–Impulse Theorem

$$\vec{J} = \vec{p}_f - \vec{p}_o$$

- ▶ *Always* valid, if impulse takes into account all forces
- ▶ *Useful way* to calculate *change in direction*
- ▶  $\vec{J}$  refers to the impulse delivered *to* an object

## Active Learning Exercise

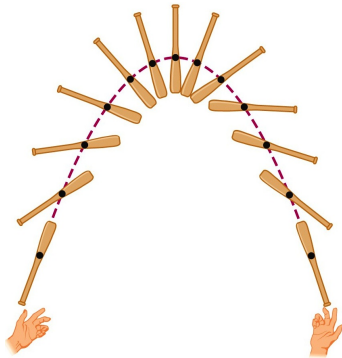
### Problem: Bounces, Recoils & Rebounds



A  $4.0$  kg zombie head is moving horizontally with a speed of  $5.0$  m/s when it strikes a vertical wall. The head rebounds with a speed of  $3.0$  m/s. What is the magnitude of the impulse delivered to the head?

## 9.1 – Center of Mass

- ▶ momentum is thought of as centered on a *point*
- ▶ this point may be on *or near* the object
- ▶ all other points rotate about the **center of mass**



## 9.1 – Center of Mass

- ▶ For  $n$  discrete particles the c.o.m. is located at

$$x_{\text{com}} = \frac{1}{M} \sum_{i=1}^n m_i x_i = \frac{m_1 x_1 + m_2 x_2 + \dots}{m_1 + m_2 + \dots}$$

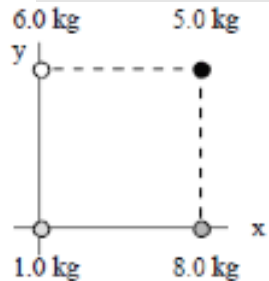
$$y_{\text{com}} = \frac{1}{M} \sum_{i=1}^n m_i y_i = \frac{m_1 y_1 + m_2 y_2 + \dots}{m_1 + m_2 + \dots}$$

$$z_{\text{com}} = \frac{1}{M} \sum_{i=1}^n m_i z_i = \frac{m_1 z_1 + m_2 z_2 + \dots}{m_1 + m_2 + \dots}$$

- ▶ Such series are called **weighted average**

## Active Learning Exercise

### Problem: Center of Mass

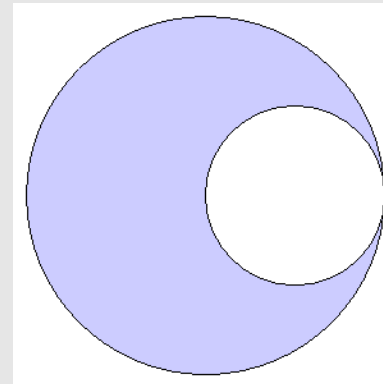


Four point masses are located at the corners of a square with sides 2.0 m, as shown. The 1.0 kg mass is at the origin. What is the vector location of the center of mass of the system?

## 9.1 – Center of Mass

Example:

Try this one!



Take  $r = 1$ , so  $m_O = \pi$

$$\begin{aligned} x_{\text{com}} &= \frac{\pi(0) + \frac{-\pi}{4} \left(\frac{1}{2}\right)}{\pi - \frac{\pi}{4}} \\ &= -\frac{1}{8} \frac{4}{3} = -\frac{1}{6} \end{aligned}$$